

Flow-based Computing on Nanoscale Crossbars: Design and Implementation of Full Adders

Zahiruddin Alamgir, Karsten Beckmann and Nathaniel Cady
SUNY Polytechnic Institute
4403 NanoFab East
257 Fuller Road
Albany, NY 12203
Email: ncady@sunypoly.edu

Alvaro Velasquez and Sumit Kumar Jha
Computer Science Department University of
Central Florida
4000 Central Florida Blvd
Orlando, FL 32765
Email: jha@eecs.ucf.edu

Abstract—We present the design and implementation of a full adder circuit that exploits the natural flow of current through nanowires and More-than-Moore nano-devices in two dimensional crossbars. We evaluate the speed and energy efficiency of our design and compare it to equivalent one-bit adder designs using CMOS and nanoscale memristors. Our memristive full adder circuit has been shown to be an order of magnitude faster and more energy-efficient than equivalent CMOS designs. Our circuit is an order of magnitude more compact than equivalent CMOS designs. We also argue that our design occupies less area and is faster than competing memristor designs.

Index Terms—Memristor, Crossbars, Adders, Sneak Paths, Digital Computing, Nanowires, Nanoscale Devices.

I. INTRODUCTION

The exponential growth in the performance of computing systems over the last forty years has climaxed with a 10,000-fold increase in individual processor speeds over the last two decades of the 20th century [1]. During this period, three things have remained invariant:

- (a) The increase in performance has come largely from the shrinking of the feature size of CMOS devices [2] reducing the voltage requirement of the circuit and permitting an increase in the clock frequency without exceeding the power budget.
- (b) John Von Neumann’s computer architecture [3] has been successfully implemented using hierarchical memory units and one or more processor units communicating using standardized on-chip interconnects and off-chip buses. This Von Neumann gap between processors and memories has traditionally been bridged using increasingly complex memory hierarchies.
- (c) There has been a clear separation between the software and hardware stacks [4] achieved using a series of optimizing compilers for standardized languages with different back-ends [5] and a strongly preserved backward-compatibility of the x86 instruction set over several generations of processors. Thus, the increasing design complexity involved in rapidly improving computing performance, such

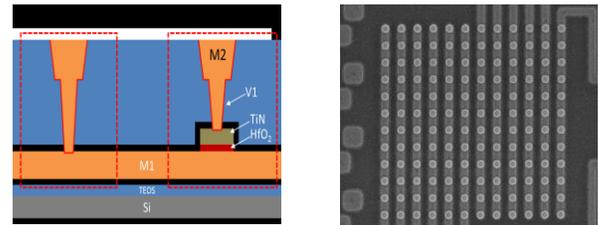


Fig. 1 (left) Schematic cross-section of a memristor used in this work. (right) SEM View of a 12x12 memristor crossbar array. Crossbar arrays were fabricated at SUNY Polytechnic Institute on 300 mm wafers using a modified IBM 65nm 10LPe process flow

as deep and speculative pipelining, not yet been achieved. The worldwide information technology industry has grown to a size of more than \$3 trillion largely because of the exponential growth in computing capacity and the sustained consistency of the programming model across multiple generations of processors. The end of Dennard scaling threatens this exponential growth and the societal expectations of faster cyberinfrastructure from scientists and the public at large.

In this paper, we respond to the crisis caused due to the end of Dennard scaling by demonstrating that the flow of current through nanoscale crossbars can be used to perform addition in a fast, energy-efficient, and compact manner. We evaluate the speed and energy efficiency of our design and compare it to equivalent one-bit adder designs using CMOS and nanoscale memristors. Our memristive full adder circuit has been shown to be an order of magnitude faster and more energy-efficient than the equivalent CMOS design. Our circuit is also an order of magnitude more compact than equivalent CMOS designs. Our results suggest a promising direction towards the development of next generation, energy efficient, and compact computing devices.

II. RELATED WORK

A. Addition Using Memristive ‘Stateful’ Logic Operation

Borghetti et al. [6] have shown that, in addition to being used as memory elements, memristors can be used as conditionally switchable logic device via so-called “material implication” or IMP operation. For example, two memristors P and Q are connected electrically through a horizontal nanowire to a load R_G . IMP is performed by two simultaneous voltage pulses, V_{COND} and V_{SET} , applied to switches P and Q, respectively, to execute conditional switching on Q, depending on the state of P. They have demonstrated that NAND logic can be executed using three memristors by repeated use of the IMP operations. Lehtonen et al. [7] showed mathematically that addition can be performed using this concept of logic-in-memory. A set of input memristors is driven to a required set of initial states and a Boolean function f of these inputs is computed sequentially or step-by-step in another set of memristors known as working memristors. As sum and carry are Boolean functions, addition can be performed using memristors through a number of such sequential computations. This scheme requires $3N+5$ devices and $88N+48$ cycles where N stands for number of bits. Kvatinisky et al. [8] presented a specific modification in the crossbar structure to introduce two improved adder designs: a parallel adder and a serial adder. Their methods have been shown (through simulation) to reduce the number of devices and the number of cycles. In their approach, the serial adder requires $3N+3$ devices and $29N$ cycles and the parallel adder requires $9N$ devices and $5N+18$ cycles of operation to perform addition. Algorithmic insight into the synthesis of nanoscale crossbars [9] and networks of crossbars [10], including fault-tolerant designs, from functional specifications have also been studied earlier. This paper focusses on the experimental characterization of one-bit full adder.

B. Addition Using Complementary Resistive Switches

Complementary resistive switching (CRS) cells are made up of two anti-serially connected ReRAM cells. Siemen et al. came up with a scheme of two multi-bit adders using CRS based logic-in-memory process [11]. This adder has reduced the number of devices and steps. CRS based adders perform addition functions on a CRS passive crossbar array by using simple consecutive signal sequences. The system consists of many crossbar arrays and a control unit to send signal to word-lines and bit-lines. The calculations take place in several steps and intermediate steps are read out or stored information is used for the next steps. In final step, information is merged and final sum bits are calculated. This group also introduced two types of adder circuits. The first one is a pre-calculation adder, requiring $2(N+1)$ devices and $2(N+1)+2$ cycles of operations. This type needs more than one wordline configured in different arrays, such as one wordline for sum calculation and other wordlines for auxiliary calculations. The second adder is a toggle cell adder that needs only one wordline in one array and requires $N+2$ devices and $4N+5$ steps.

C. Addition Using CMOS

The most common CMOS adder circuit is 28 transistor (28T) adder. To fulfill different constraints such as area, power and

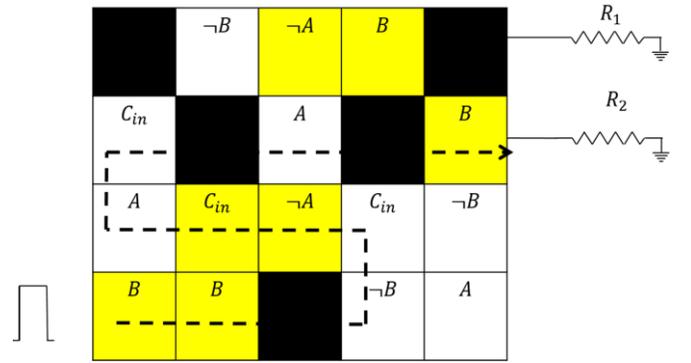


Fig. 2. The optimized design of a one-bit adder using sneak paths in a nanoscale memristor crossbar array. The black filled squares represent turned-off memristors and other squares denote a literal or its negation. The dashed blue arrow indicates the flow of sneak current from the lowest row to the third row when the inputs are: $A = 1$, $B = 0$, and $C = 1$.

speed, several CMOS based adders are being proposed such as Transmission Gate (TG) adder, Pass Transistor Logic (PTL) adder, and Gate Diffusion Input (GDI) adder. Each of these designs has its own merits and shortcomings. For example, conventional 28T adder circuit has high noise margin and reliable operation at low voltage. But the large number of transistors causes higher power consumption and a larger area. A full adder can be designed by implementing multiplexers and XORs as transmission gates. This type of adder has the fastest speed, but suffers from higher power dissipation compared to 28T adder.

All of the memristor-based adder schemes described above have only been demonstrated by means of simulation. This is perhaps because memristor-based adder operation requires an additional control unit to send control signals and to store memory in case of intermediate destructive reading. No comparison of latency, power or energy consumption with CMOS based adders have been described to date. As the adder schemes described above operate sequentially in several steps, it can be argued that latency could be substantially higher than that of CMOS adder circuit.

III. DESIGN AND IMPLEMENTATION OF THE FULL ADDER

Our design for a one-bit adder is shown in Figure. 2. Here, the black filled squares represent turned-off (high resistance) memristors and other squares denote a literal or its negation. The input bits are A and B , and the carry-in bit is C_{in} . A Boolean value ‘False’ or ‘0’ corresponds to a turned-off memristor, and the Boolean value ‘True’ or ‘1’ corresponds to a turned-on memristor. The crossbar design can compute Sum and C_{out} by applying a voltage at the bottom wire. A large current will flow along the first row when Sum is ‘True’ or ‘1’ and a negligible amount of current would flow when Sum is ‘False’ or ‘0’. Similarly, a large current will flow along the second row when ‘ C_{out} ’ is ‘1’ and negligible current will flow when ‘ C_{out} ’ logic level is ‘0’. As a result, If we add high resistive loads R_1 and R_2 ($R_1=R_2=50$ k Ω) at the output of the first and the second row, voltage drop across R_1 (V_{R1}) will be much higher than the voltage drop across R_2 (V_{R2}) when Sum is ‘1’ and C_{out} is ‘0’ and vice versa. When both Sum and C_{out}

are '0' or both are '1', voltage drops across both loads will be negligible or high, respectively.

To clarify how the sneak current flows to differentiate logic levels, we present a specific example where inputs were $A=1, B=0, C_{in}=1$. Each block represents a memristor at the crossbar junction: black boxes are turned off memristors, yellow boxes are memristors that are turned off for this input combination, and white boxes are turned on (low resistance state) memristors according to the design explained above. In Figure 2, the dotted line shows the flow of sneak current when a voltage is applied at the bottom row. In this case, the sneak current flows through the C_{out} nanowire and the voltage drop across R_2 is much higher than the voltage across R_1 . As a result, C_{out} would be evaluated as 'High'.

In order to study the performance of our full adder designs experimentally, crossbar arrays (12×12) were implemented on a 300 nm wafer platform in a back-end-of-the-line (BEOL) process. The IBM 65 nm 10LPe process was used as the mainframe to integrate a custom build ReRAM layer between metal 1 (M1) and metal 2 (M2). Metal 1 was fabricated in a damascene process where 100 nm lines were etched into the SiO_2 insulating layer and subsequently filled with a line consisting of TaN/Ta followed by electroplated Cu. After a planarization step the HfOx layer was deposited in a reactive PVD process and subsequently served as the active part of the memristor. A subsequent TiN deposition created the top electrode and in a RIE step followed by a wet etch the 12×12 memristor elements were defined in the size of $100 \times 100 \text{ nm}^2$ on top of M1. By depositing SiO_2 the active layer was encapsulated and the M2 insulation was fabricated. A final dual-damascene step created the 100 nm wide M2 trenches and V1 holes to connect to the created TiN top electrode. M2/V1 got fabricated by putting down the liner (TaN/Ta) and again electroplating Cu. A final planarization step removed the excess copper resulting in insulated M2 lines. For our adder circuit implementation, we used 4×5 sub-matrix in a corner of our 12×12 matrix array.

A. Experimental Verification

The adder operation was performed in two steps. In the first step, the array was configured to one of the input combinations. In a commercial realization, a control circuit might be used to change one input state to another input state. In the second step, pulse voltages of 0.1 volt ($\sim 100 \text{ mV}$) and 0.2 volt ($\sim 200 \text{ mV}$) were applied in the bottom row and the voltages across R_1 and R_2 for all the input configurations of the 1-bit adder were measured. In all the cases, output voltages corresponded to the expected logic levels. The output voltage for output logic level '1' was at least 20 times higher than that for output logic level '0'. For example, when the inputs are $A=1, B=1, C=0$, the output logic levels are: $Sum = 0, C_{out} = 1$. In this case, $V_{R1} = 1.77 \text{ mV}$ and $V_{R2} = 98.04 \text{ mV}$ were found. In this case, $V_{R2}/V_{R1} = 55$. As a result, the probability of noise margin error would be very low. The experimental results are summarized in the Table 1.

B. Speed and Energy-Efficiency of Computation

Any arithmetic operation such as addition, in broad view, requires four basic steps in Arithmetic Logic Unit (ALU) in a microprocessor – a) loading the address of the data, b)

moving the content of the memory location into

TABLE I
OUTPUT CURRENTS FOR DIFFERENT INPUT COMBINATIONS

Input			Output Voltages (mV)		Output Logics	
A	B	C_{in}	$Sum(V_{R1})$	$C_{out}(V_{R2})$	Sum	Cout
0	0	0	0.94	1.33	0	0
0	0	1	95.53	0.74	1	0
0	1	0	98.50	0.79	1	0
0	1	1	1.04	98.43	0	1
1	0	0	98.95	0.84	1	0
1	0	1	4.58	98.42	0	1
1	1	0	1.77	98.04	0	1
1	1	1	97	99.04	1	1

accumulator, c) adding the content of the memory location, and d) moving the accumulator content to memory location. These events proceed with clock cycles. The first two steps can be considered as pre-computing steps. The power and propagation delay of pre-computing step of memristive adder depend on switching power and speed. It can be noted that, Torrezan et al. have shown sub nanosecond switching of tantalum oxide memristor [12, 13]. This fast switching could be attributed to the reasons that ionic species move a fairly short distance (1 nm or less) during switching and Joule heating significantly enhances the mobility of the ionic species [14]. Hence, we will compare the delay and power of computation step of CMOS adder and the proposed memristive adder.

The speed of computation depends on the delay between the input and output signals. The delay measurement was limited by the electrical testing instrument currently available in our laboratories. As an alternative, Cadence Spectra circuit simulator (SPICE level simulator), tightly integrated with virtuoso custom design platform, was used to design a schematic of a 4×5 crossbar array and a 28T CMOS adder and to simulate propagation delay and other metrics of both type of adders. Our crossbar array was fabricated on the IBM 65 nm CMOS 10LPe Low Power technology platform. Line resistances and other parasitic capacitances such as lateral capacitance, fringe capacitance etc. were extracted for simulation following IBM 10LPe design specifications. The on state memristor resistance values were set to 1 k Ω , and the turned off memristor resistances were set to 1 M Ω . The 28T adder was designed based on the same technology platform and optimal transistor size was used to maintain optimal delay. For CMOS, current and voltage drops are negligible due to a pull-up, pull-down network. But in crossbar adders, the

TABLE II
PERFORMANCE METRICS COMPARISON

	28T(1GHz)	Crossbar (1Volt input)	Crossbar (0.2 Volt input)
Propagation Delay (ps)	39	1.4	1.3
Power (μw)	4.68	22.5	1
PDP ($\times 10^{-17}$ Joules)	182.52	31.5	1.3

voltage drops occur along the sneak path. Hence, we added a higher resistance (50 k Ω) as the load in simulation so that sufficient voltage can be obtained at output node to drive the next stage. All the input combinations were simulated using 1 V, and 200 mV voltage pulses with 300 ps pulse width having 50% duty cycle. For 28T adder 980 MHz (\sim 1 GHz) clock pulse and 1.2 volts bias were used. For CMOS the average power was calculated using $P_{avg} = V_d \int_0^T i(t) dt$ where T is the time period when all possible input combinations took place. For the crossbar adder, the same expression is used and the results are averaged over all possible input combinations. Propagation delay of the crossbar adder was found to be very low compared to the CMOS adder in the simulation. For the crossbar adder, power consumption for a 1 V input pulse was higher than that of the CMOS adder. And, in the case of a 200 mV input pulse, the memristive crossbar adder provided extremely low power operation. So for 100 mV input voltage, the power consumption would be even lower. In terms of Power Delay Product (PDP), multiplication of power and propagation delay, which is energy per operation, the memristive crossbar adder seems to be a better candidate than the CMOS implementation.

C. Area

As memristors have excellent scalability, crossbar based adders have an advantage over CMOS adders in terms of total circuit area. The dimensions of our 4×5 crossbar array were 640 nm \times 1000 nm and so the area of the crossbar adder circuit was 0.64 μm^2 . The conventional 28T CMOS full adder circuit based on 65 nm technology has an area of 10 μm^2 , which is approximately 15 times higher than our memristor crossbar based adder. Again, 10 nm \times 10 nm HfO₂ based ReRAM has been reported [15]; thus, crossbar based adders of significantly reduced area are possible. As a full adder circuit is a building block of other arithmetic operations, such as subtraction, multiplication, and division in microprocessors, the scalability of memristor crossbar arrays can be leveraged to create arithmetic and logic circuits of much reduced area using non-volatile memory storage device.

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